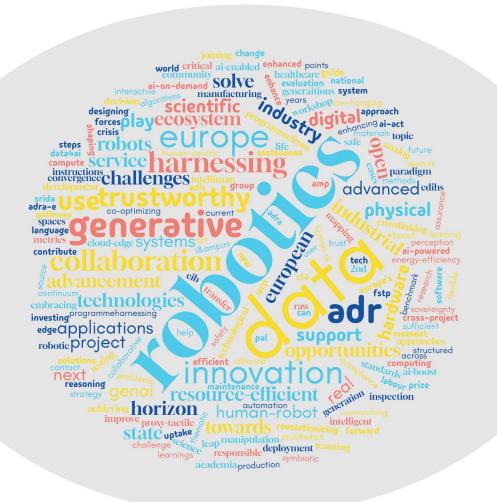


## Where is the value?









### What is EQUINOR?

Equinor is the operator of the world largest offshore wind farm Dogger Bank in the UK.



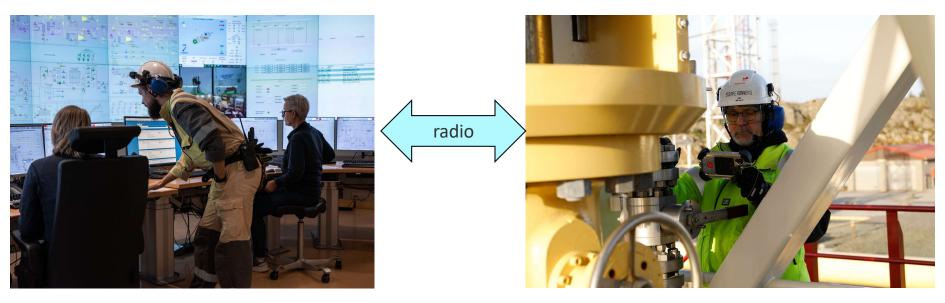
Norway supply approximately 30% of all gas used by Europe and Equinor is by far the largest operator in Norway.

3 | Oper



# Current solution: Control room operator communicate with an operator in the field



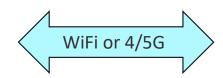


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## Current solution for robot in operation: Mission programming software available in the control room











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### SW stack for current solution using robots



Operator interface to all plant data

Digital twin w geo data



Robot mission programming operator interface

Generic robot mission steps

Translation layer to to robot specific API

**Robot API** 

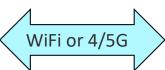




## Desired state: The robot can interact directly with the control operator (voice control)









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## Proposed SW stack: The mission programing component can understand the voice control



Operator interface to all plant data

LLM (in native language) for interpretation of voice commands to the robot



Digital twin w geo data



Generic robot mission steps

Translation layer to robot specific API

**Robot API** 



Key insight of the use of AI & LLM in the widespread introduction of robotics



- ➤ Change management is hard technology easier
- Voice commanded robots will significantly lower the barriers to widespread use of robots
- ➤ Voice controlled mission programming adds value to the use of robotics in inspection and maintenance by reducing complexity of robot user interface (mission programming, fleet management) and need for operator training.
- ➤ Voice control must be in the user's native language. Example: in the Energy industry on the Norwegian Continental Shelf, the use of the Norwegian language in operation is regulated by law due to safety.

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### **Autonomous Inspection Robots**

**EQUINOR TDI Asset Autonomy Robotics and Drones** 

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